

用U变换法分析薄壁箱形连续梁 的组合扭转*

陈森炎 蔡承武
(应用力学与工程系)

摘要 用U变换法分析具有周期性支承的薄壁箱形连续梁的组合扭转。连续梁的控制方程经U变换解耦后,建立了子结构规模的控制方程和边界条件,并结合具体载荷条件,给出了位移和内力相应的解析表达式。

关键词 U变换, 组合扭转, 双力矩

1 基本方程

具均匀抗弯刚度 $E'I_{\omega a}$ 与抗扭刚度 GI_k 的 n 跨薄壁箱形连续梁(图1(a)), 其子结构跨长为 l 。为形成等价的旋转周期系统, 以原连续结构右外端支承为中心, 结构对称、荷载反对称拓展, 并使延拓结构末端与原结构始端的支承条件一致(令两端的广义扭率、双力矩相等)见图1(b)。于子结构上建立局部坐标系, 设原点位于跨中点处, 在局部坐标中建立的扭转微分方程为

$$d^4\phi_k(x)/dx^4 - \lambda^2 d^2\phi_k(x)/dx^2 = \mu/E'I_{\omega a} \cdot m_k(x) \quad \left(-\frac{l}{2} < x < \frac{l}{2}, k=1, 2, \dots, N\right) \quad (1)$$

其中 $N=2n$, $\phi_k(x)$ 为扭角位移函数, λ 为截面弯扭特性系数 ($\lambda^2 = \mu GI_k / E'I_{\omega a}$), μ 为截面翘曲系数, $I_{\omega a}$ 为截面广义主扇性惯矩, $m_k(x)$ 为第 k 子结构的荷载函数。

方程(1)应满足下列条件

$$\left. \begin{aligned} \phi_k|_{x=l/2} &= \phi_k|_{x=-l/2} = 0 \\ \dot{\theta}_k|_{x=l/2} &= \dot{\theta}_{k+1}|_{x=-l/2} \quad (1) \\ B_{wk}|_{x=l/2} &= B_{wk+1}|_{x=-l/2} \end{aligned} \right\} \quad (2)$$

其中 $\dot{\theta}_k$ 为广义扭率, B_{wk} 为双力矩。

本文1991年12月4日收到

* 国家自然科学基金资助项目

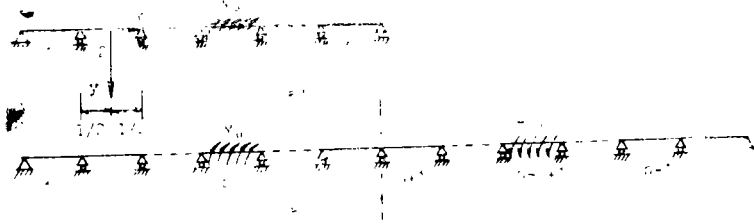


图 1 作用均布扭矩薄壁箱形连续梁

Fig. 1 Thin walled box girder with periodic supports to a distributed torque of constant intensity M_0

(a) 实际体系; (b) 等效体系

由周期结构的旋转性质，方程 (1) 还应满足约束条件

$$\left. \begin{aligned} \phi_N|_{x=l/2} &= \phi_1|_{x=-l/2} \\ \dot{\theta}_N|_{x=l/2} &= \dot{\theta}_1|_{x=-l/2} \\ B_{wN}|_{x=l/2} &= B_{w1}|_{x=-l/2} \end{aligned} \right\} \quad (3)$$

将方程 (1)，式 (2) 和 (3) 写成矩阵形式

设 $\{\phi\} = [\phi_1 \phi_2 \dots \phi_N]^T$; $\{m\} = [m_1 m_2 \dots m_N]^T$

则有

$$d^4\{\phi\}/dx^4 - \lambda^2 d^2\{\phi\}/dx^2 = \mu/E'I_{\omega a} \{m\} \quad (4)$$

和

$$\left. \begin{aligned} \{\phi\}|_{x=l/2} &= \{\phi\}|_{x=-l/2} = \{0\} \\ \{\phi'\}|_{x=l/2} + \frac{1}{\mu k^2} \{\phi''\}|_{x=l/2} &= [\varepsilon]^0 \left[\{\phi'\}|_{x=-l/2} + \frac{1}{\mu k^2} \{\phi''\}|_{x=-l/2} \right] \\ \beta E'I_{\omega a} \{\phi''\}|_{x=l/2} + \frac{1}{k^2} \{m\}|_{x=l/2} &= [\varepsilon]^0 \left[\beta E'I_{\omega a} \{\phi''\}|_{x=-l/2} + \frac{1}{k^2} \{m\}|_{x=-l/2} \right] \end{aligned} \right\} \quad (5)$$

其中, $k^2 = \frac{\mu G I_{\rho}}{E' I_{\omega a}}$, $\beta = \frac{1}{\mu}$

$$[\varepsilon]^0 = \begin{bmatrix} 0 & 1 & & & \\ & 0 & \dots & 1 & \\ & \vdots & \dots & \vdots & \dots \\ & \vdots & \dots & \vdots & \dots \\ 1 & 0 & & & 0 \end{bmatrix}_{N \times N}$$

为解除 (5) 连续条件耦合，需进行下列线性变换^[2~4]

设 $\{\phi\} = [U]\{q\} \quad (6)$

$$\left. \begin{aligned} \{q\} &= [q_1 \ q_2 \ \dots \ q_N]^T \\ [U] &= [U_1 \ U_2 \ \dots \ U_N] \end{aligned} \right\} \quad (7)$$

$[U]$ 的矢分量为

$$\{U_k\} = N^{-1/2} [1 \ \exp(ik\phi) \ \exp(i2k\phi) \ \dots \ \exp(i(N-1)k\phi)]^T \quad (8)$$

其中, $\phi = 2\pi/N$, $i = \sqrt{-1}$, $\{q\}$ 的分量 $q_k (k=1, 2, \dots, N)$ 称广义位移 (或旋转坐标)。

$[U]$ 有下列特性^[2]:

$$[U]^T[U] = [I] \quad (9)$$

$$[U]^T[\varepsilon]^0[U] = [e^{i\psi} \ e^{i2\psi} \ \dots \ e^{iN\psi}] \quad (10)$$

其中, $[U]^T$ 表示 $[U]$ 的复共轭转置矩阵, $[I]$ 为单位矩阵, $[U]$ 满足式(9)称 U 矩阵, 而式(6)则称 U 变换。

将(7)和(8)代入(6)则得

$$\phi_k = \frac{1}{\sqrt{N}} \sum_{m=1}^N \exp[i(k-1)m\psi] q_m, \quad (k=1, 2, \dots, N) \quad (11)$$

这里(11)与(6)是等同的。

将(6)代入(4)和(5)并两端左乘 $[U]^T$ 得

$$d^4\{q\}/dx^4 - \lambda^2 d^2\{q\}/dx^2 = \{f\}, \quad \left(-\frac{l}{2} < x < \frac{l}{2}\right) \quad (12)$$

和

$$\left. \begin{aligned} \{q\}|_{x=l/2} = \{q\}|_{x=-l/2} = \{0\} \\ \{q'\}|_{x=l/2} + \frac{1}{\mu k^2} \{q''\}|_{x=l/2} = [U]^T[\varepsilon]^0[U] \left[\{q'\}|_{x=-l/2} + \frac{1}{\mu k^2} \{q''\}|_{x=-l/2} \right] \\ \{q''\}|_{x=l/2} + \frac{1}{k^2} \{f\}|_{x=l/2} = [U]^T[\varepsilon]^0[U] \left[\{q''\}|_{x=-l/2} + \frac{1}{k^2} \{f\}|_{x=-l/2} \right] \end{aligned} \right\} \quad (13)$$

其中, $\{f\} = [U]^T \frac{\mu}{E'I \dot{w}_a} \{m\}$

由(12)、(13)则得 N 组单一子结构的微分方程

$$d^4 q_m/dx^4 - \lambda^2 d^2 q_m/dx^2 = f_m(x), \quad \left(-\frac{l}{2} < x < \frac{l}{2}, m=1, 2, \dots, N\right) \quad (14)$$

和

$$\left. \begin{aligned} q_m|_{x=l/2} = q_m|_{x=-l/2} = 0 \\ \left(q'_m + \frac{1}{\mu k^2} q''_m \right) \Big|_{x=l/2} = e^{im\psi} \left(q'_m + \frac{1}{\mu k^2} q''_m \right) \Big|_{x=-l/2} \\ \left(q''_m + \frac{f_m}{k^2} \right) \Big|_{x=l/2} = e^{im\psi} \left(q''_m + \frac{f_m}{k^2} \right) \Big|_{x=-l/2} \end{aligned} \right\} \quad (15)$$

其中 $f_m(x) = \frac{\mu}{E'I \dot{w}_a} \cdot \frac{1}{\sqrt{N}} \sum_{k=1}^N \exp[-i(k-1)m\psi] m_k(x) \quad (16)$

在(15)边界条件下, 解方程(14)可得位移函数 $\phi_k(x)$ 与相应内力 $B_{wk}(x)$, $k=1, 2, \dots, N$ 。对 $\phi_k(x)$ 取极限($N \rightarrow \infty$), 则可得无限跨箱形连续梁的位移函数 $\phi_k^*(x)$ 与相应内力 $B_{wk}^*(x)$, $k=1, 2, \dots, N$ 。

2 连续梁在均布扭矩载荷作用下的扭角与双力矩

图1(a)原系统为 n 跨薄壁箱形连续梁, 均布外扭矩 M_0 作用于第 s 跨。为获得等价的旋转周期系统, 将结构、载荷拓展为 $2n$ 跨周期结构, 且 $-M_0$ 作用于第 $2n-s+1$ 跨见图1(b)。考虑 s 为中间跨, 即 $n=2s-1$, $N=2n=(2s-1)$, 荷载函数为

$$m_s(x) = M_0, \quad m_{N-s+1}(x) = -M_0, \quad m_j(x) = 0 \quad j \neq s, N-s+1 \quad (17)$$

将(17)代入(16)并注意 $\phi = \frac{2\pi}{N}$ 得

$$f_m(x) = \begin{cases} \frac{\mu}{E'I\psi a} \cdot \frac{2M_0}{\sqrt{N}} \exp[-i(s-1)m\phi] & (m=1,3,\dots,N-1) \\ 0 & (m=2,4,\dots,N) \end{cases} \quad (18)$$

(18)代入方程(14)得

$$d^4 q_m / dx^4 - \lambda^2 d^2 q_m / dx^2 = \frac{\mu}{E'I\psi a} \cdot \frac{2M_0}{\sqrt{N}} \exp[-i(s-1)m\phi] \quad (19)$$

$$\left(-\frac{l}{2} < x < \frac{l}{2}, m=1,3,\dots,N-1\right)$$

方程(19)在(15)边界条件下的解为

$$q_m(x) = \begin{cases} (C_{m0} + C_{m1}x + C_{m2} \operatorname{sh} \lambda x + C_{m3} \operatorname{ch} \lambda x - x^2)(f_m/2\lambda^2) & (m=1,3,\dots,N-1) \\ 0 & (m=2,4,\dots,N) \end{cases} \quad (20)$$

其中,

$$\left. \begin{aligned} C_{m0} &= \left(\frac{l}{2}\right)^2 - \frac{c+d-(c-d)\operatorname{cos}m\phi}{e-f\operatorname{cos}m\phi} \operatorname{ch} \frac{\lambda l}{2} \\ C_{m1} &= -i \frac{(a-b) \cdot \operatorname{sin}m\phi}{e-f\operatorname{cos}m\phi} \cdot \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \\ C_{m2} &= i \frac{(a-b) \cdot \operatorname{sin}m\phi}{e-f\operatorname{cos}m\phi} \\ C_{m3} &= \frac{c+d-(c-d) \cdot \operatorname{cos}m\phi}{e-f\operatorname{cos}m\phi} \end{aligned} \right\} \quad (21)$$

式中

$$\begin{aligned} a &= \lambda^2 l \operatorname{ch} \frac{\lambda l}{2}, \quad b = \left(2 - \frac{2\lambda^2}{k^2}\right) \left(\lambda + \frac{\lambda^3}{\mu k^2}\right) \cdot \operatorname{sh} \frac{\lambda l}{2}, \\ c &= \left(2 - \frac{2\lambda^2}{k^2}\right) \left[\left(\lambda + \frac{\lambda^3}{\mu k^2}\right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2}\right], \quad d = \lambda^2 l \operatorname{sh} \frac{\lambda l}{2}, \\ e &= \lambda^2 \operatorname{ch} \frac{\lambda l}{2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2}\right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2}\right] + \lambda^2 \operatorname{sh}^2 \frac{\lambda l}{2} \left(\lambda + \frac{\lambda^3}{\mu k^2}\right), \\ f &= \lambda^2 \operatorname{ch} \frac{\lambda l}{2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2}\right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2}\right] - \lambda^2 \operatorname{sh}^2 \frac{\lambda l}{2} \left(\lambda + \frac{\lambda^3}{\mu k^2}\right). \end{aligned}$$

将(20)、(21)代入(11)则得各子结构的位移函数 $\phi_k(x)$ ($k=1,2,\dots,N$)。由(14)、(15)的数学特征得知, $\phi_k(x)$ 将为实函数, 故(11)应改写为

$$\phi_k = \frac{1}{\sqrt{N}} \sum_{m=1}^N \operatorname{Re}[\exp[i(k-1)m\phi] q_m] \quad (k=1,2,\dots,N) \quad (22)$$

用(20)、(21)代入(22)便得连续梁的扭转角

$$\phi_s(x) = \frac{1}{N} \frac{M_0}{GI_k} \sum_{m=1,3,\dots}^{N-1} \left[\left(\frac{l}{2}\right)^2 + \left(\operatorname{ch} \lambda x - \operatorname{ch} \frac{\lambda l}{2}\right) \frac{c+d-(c-d)\operatorname{cos}m\phi}{e-f\operatorname{cos}m\phi} - x^2 \right] \quad \left(-\frac{l}{2} \leq x \leq \frac{l}{2}\right) \quad (23)$$

这里的 $\phi_s(x)$ 指载荷跨 (第 s 跨) 的扭转角, 其它跨 ($k \neq s$) 同样不难得到, 最大扭转角发生于载荷跨跨中

$$\begin{aligned} \phi_{\max} &= \phi_s(0) \\ &= \frac{1}{N} \frac{M_0}{GI_k} \sum_{m=1,3,\dots}^{2n-1} \left[\left(\frac{l}{2}\right)^2 + \left(1 - \operatorname{ch} \frac{\lambda l}{2}\right) \frac{c+d - (c-d)\cos m\phi}{e - f\cos m\phi} \right] \end{aligned} \quad (24)$$

最大双力矩发生于载荷跨跨端

$$\begin{aligned} B_{w\max} &= -\beta E' I_{\omega a} \phi_s'' \left(\pm \frac{l}{2}\right) - \frac{M_0}{k^2} \quad \left(\text{其中 } \beta = \frac{1}{\mu}\right) \\ &= \frac{M_0}{N} \sum_{m=1,3,\dots}^{2n-1} \left[\frac{2}{\lambda^2} - \operatorname{ch} \frac{\lambda l}{2} \cdot \frac{c+d - (c-d)\cos m\phi}{e - f\cos m\phi} \right] - \frac{M_0}{k^2} \end{aligned} \quad (25)$$

现考察(23)右边级数的各项总和,有如下一般形式

$$I_n = \frac{1}{n} \sum_{m=1,3,\dots}^{2n-1} f(m\phi) = \frac{1}{n} \sum_{m=1,3,\dots}^{2n-1} f\left(\frac{m\pi}{n}\right) \quad (26)$$

设 $\Delta\theta = \frac{2\pi}{n}$, 式(26)则有

$$I_n = \frac{1}{2\pi} \sum_{m=1,3,\dots}^{2n-1} f\left(\frac{m}{\sqrt{2}}\Delta\theta\right)\Delta\theta$$

当 n 趋于无穷时,级数 I_n 的极限可表示为如下的积分

$$\lim_{n \rightarrow \infty} \frac{1}{n} \sum_{m=1,3,\dots}^{2n-1} f(m\phi) = \frac{1}{2\pi} \int_0^{2\pi} f(\theta) d\theta \quad (0 \leq \theta \leq 2\pi) \quad (27)$$

将这关系用于(23),便得无限跨连续梁的扭转角

$$\begin{aligned} \phi_s^*(x) &= \lim_{n \rightarrow \infty} \phi_s(x) \\ &= \frac{M_0}{2GI_k} \left\{ \left(\frac{l}{2}\right)^2 + \left(\operatorname{ch} \lambda x - \operatorname{ch} \frac{\lambda l}{2}\right) \left[\frac{Af - Be + B(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}}{f(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}} \right] - x^2 \right\} \\ &\quad - \frac{l}{2} \leq x \leq \frac{l}{2} \end{aligned} \quad (28)$$

最大扭转角发生于跨中

$$\begin{aligned} \phi_{\max}^*(x) &= \phi_s^*(0) \\ &= \frac{M_0}{2GI_k} \left\{ \left(\frac{l}{2}\right)^2 + \left(1 - \operatorname{ch} \frac{\lambda l}{2}\right) \left[\frac{Af - Be + B(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}}{f(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}} \right] \right\} \end{aligned} \quad (29)$$

最大双力矩发生于跨端

$$\begin{aligned} B_{w\max}^* &= -\beta E' I_{\omega a} \phi_s^{*''} \left(\pm \frac{l}{2}\right) - \frac{M_0}{k^2} \\ &= \frac{M_0}{2} \left\{ \frac{2}{\lambda^2} - \operatorname{ch} \frac{\lambda l}{2} \left[\frac{Af - Be + B(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}}{f(e+f)\left(\frac{e-f}{e+f}\right)^{1/2}} \right] \right\} - \frac{M_0}{k^2} \end{aligned} \quad (30)$$

$$\text{其中, } A = \left(2 - \frac{2\lambda^2}{k^2}\right) \left[\left(\lambda + \frac{\lambda^3}{\mu k^2}\right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] + \lambda^2 l \operatorname{sh} \frac{\lambda l}{2},$$

$$B = \left(2 - \frac{2\lambda^2}{k^2} \right) \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] - \lambda^2 l \operatorname{sh} \frac{\lambda l}{2}, \quad e, f \text{ 同前.}$$

3 连续梁在集中扭矩载荷作用下的扭角与双力矩

如图2(a)所示,原系统为 n 跨薄壁箱形连续梁,集中外扭矩 M 作用于第 s 跨中间处.拓展后的旋转周期系统为 $2n$ 跨周期结构;且集中扭矩 $-M$ 作用于第 $2n-s+1$ 跨中间处见图2(b),荷载函数为

$$m_s(x) = M\delta(x), \quad m_{N-s+1}(x) = -M\delta(x); \quad m_j(x) = 0 \quad j \neq s, N-s+1 \quad (31)$$

其中 $\delta(x)$ 为 Dirac delta 函数.

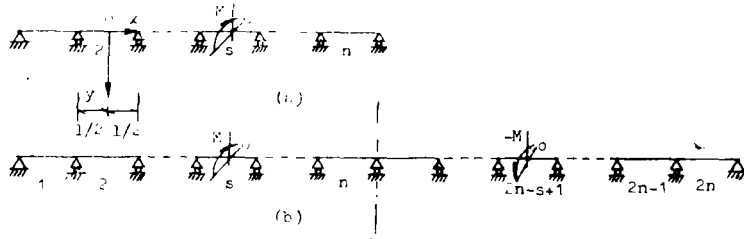


图2 作用集中扭矩薄壁箱形连续梁

Fig.2 Thin walled box girder with periodic supports to a torque M
(a) 实际体系; (b) 等效体系

将(31)代入(16)得

$$f_m(x) = \begin{cases} \frac{\mu}{E'I} \cdot \frac{2M}{\omega a} \exp[-i(s-1)m\phi] \cdot \delta(x) & (m=1,3,\dots,N-1) \\ 0 & (m=2,4,\dots,N) \end{cases} \quad (32)$$

(32)代入方程(14)则得

$$d^4 q_m / dx^4 - \lambda^2 d^2 q_m / dx^2 = \frac{\mu}{EI} \cdot \frac{2M}{\omega a} \exp[-i(s-1)m\phi] \delta(x) \quad \left(-\frac{l}{2} < x < \frac{l}{2}, m=1,3,\dots,N-1 \right) \quad (33)$$

方程(33)在(15)边界条件下的解为

$$q_m(x) = \begin{cases} (C_{m0} + C_{m1}x + C_{m2} \operatorname{sh} \lambda x + C_{m3} \operatorname{ch} \lambda x - x) (\bar{f}_m / 2\lambda^2), & 0 \leq x \leq \frac{l}{2} \\ (C_{m0} + C_{m1}x + C_{m2} \operatorname{sh} \lambda x + C_{m3} \operatorname{ch} \lambda x + x) (\bar{f}_m / 2\lambda^2), & -\frac{l}{2} \leq x \leq 0 \end{cases} \quad (34)$$

$m=1,3,\dots,N-1$

其中, $\bar{f}_m = \frac{\mu}{EI} \cdot \frac{2M}{\omega a} \exp[-i(s-1)m\phi]$

$$\left. \begin{aligned} C_{m0} &= \frac{l}{2} + \frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \cdot \operatorname{cos} m\phi}{e - f \operatorname{cos} m\phi} \cdot \operatorname{ch} \frac{\lambda l}{2} \\ C_{m1} &= -i \frac{(\bar{a} + \bar{b}) \cdot \operatorname{sin} m\phi}{e - f \operatorname{cos} m\phi} \cdot \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \\ C_{m2} &= i \frac{(\bar{a} + \bar{b}) \cdot \operatorname{sin} m\phi}{e - f \operatorname{cos} m\phi} \\ C_{m3} &= -\frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \operatorname{cos} m\phi}{e - f \operatorname{cos} m\phi} \end{aligned} \right\} \quad (35)$$

$$\begin{aligned} \text{式中, } a &= \lambda^2 \operatorname{ch} \frac{\lambda l}{2}, \quad b = \frac{2\lambda^2}{k^2} \left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \cdot \operatorname{sh} \frac{\lambda l}{2}, \\ c &= \frac{2\lambda^2}{k^2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right], \quad d = \lambda^2 \operatorname{sh} \frac{\lambda l}{2}, \\ e &= \lambda^2 \operatorname{ch} \frac{\lambda l}{2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] + \lambda^2 \operatorname{sh}^2 \frac{\lambda l}{2} \left(\lambda + \frac{\lambda^3}{\mu k^2} \right), \\ f &= \lambda^2 \operatorname{ch} \frac{\lambda l}{2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] - \lambda^2 \operatorname{sh}^2 \frac{\lambda l}{2} \left(\lambda + \frac{\lambda^3}{\mu k^2} \right). \end{aligned}$$

将(35)、(34)代入(22)则得连续梁的扭转角

$$\phi_s(x) = \begin{cases} \frac{1}{N} \frac{M}{GI_k} \sum_{m=1,3,\dots}^{N-1} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - \operatorname{ch} \lambda x \right) \frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \cos m\phi}{e - f \cos m\phi} - x \right] \\ \quad \left(0 \leq x \leq \frac{l}{2} \right) \\ \frac{1}{N} \frac{M}{GI_k} \sum_{m=1,3,\dots}^{N-1} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - \operatorname{ch} \lambda x \right) \frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \cos m\phi}{e - f \cos m\phi} + x \right] \\ \quad \left(-\frac{l}{2} \leq x \leq 0 \right) \end{cases} \quad (36)$$

最大扭转角发生于载荷跨跨中

$$\phi_{\max} = \frac{1}{N} \frac{M}{GI_k} \sum_{m=1,3,\dots}^{N-1} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - 1 \right) \frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \cos m\phi}{e - f \cos m\phi} \right] \quad (37)$$

最大双力矩发生于载荷跨跨端

$$B_{w\max} = \frac{M}{N} \sum_{m=1,3,\dots}^{N-1} \left[\operatorname{ch} \frac{\lambda l}{2} \cdot \frac{\bar{c} - \bar{d} - (\bar{c} + \bar{d}) \cos m\phi}{e - f \cos m\phi} \right] \quad (38)$$

对(36)右边级数取极限, 便得无限跨连续梁的扭转角

$$\phi_s^*(x) = \lim_{n \rightarrow \infty} \phi_s(x) = \begin{cases} \frac{M}{2GI_k} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - \operatorname{ch} \lambda x \right) \frac{\bar{A}f - \bar{B}e + \bar{B}(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}}{f(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}} - x \right] \\ \quad \left(0 \leq x \leq \frac{l}{2} \right) \\ \frac{M}{2GI_k} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - \operatorname{ch} \lambda x \right) \frac{\bar{A}f - \bar{B}e + \bar{B}(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}}{f(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}} + x \right] \\ \quad \left(-\frac{l}{2} \leq x \leq 0 \right) \end{cases} \quad (39)$$

最大扭转角发生于跨中

$$\phi_{\max}^*(x) = \frac{M}{2GI_k} \left[\frac{l}{2} + \left(\operatorname{ch} \frac{\lambda l}{2} - 1 \right) \frac{\bar{A}f - \bar{B}e + \bar{B}(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}}{f(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}} \right] \quad (40)$$

最大双力矩发生于跨端

$$B_{\omega\max}^* = \frac{M}{2} \left[\operatorname{ch} \frac{\lambda l}{2} \cdot \frac{\bar{A}f - \bar{B}e + \bar{B}(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}}{f(e+f) \left(\frac{e-f}{e+f} \right)^{1/2}} \right] \quad (41)$$

其中,
$$\bar{A} = \frac{2\lambda^2}{k^2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] - \lambda^2 \operatorname{sh} \frac{\lambda l}{2},$$

$$\bar{B} = \frac{2\lambda^2}{k^2} \left[\left(\lambda + \frac{\lambda^3}{\mu k^2} \right) \operatorname{ch} \frac{\lambda l}{2} - \frac{2}{l} \operatorname{sh} \frac{\lambda l}{2} \right] + \lambda^2 \operatorname{sh} \frac{\lambda l}{2}, \quad e, f \text{ 同前.}$$

U 变换法用于周期性连续系统的组合扭转分析, 不仅具有未知量少, 计算结果准确的优点, 同时可以有效地利用结构的周期性来提高计算效率。

参 考 文 献

- 1 黄剑源编. 薄壁结构的扭转分析. 上册. 北京: 中国铁道出版社, 1983
- 2 蔡承武. 旋转周期结构的分析解, 中山大学学报(自然科学版), 1986(2): 64~72
- 3 Cai C W, Cheng Y K, Chan H C. J Sound and Vibration, 1988, 123(3):461~472
- 4 Cheng Y K, Chan H C, Cai C W. ASCE J Engineering Mechanics, 1989, 115(2):415~434

Analysis of Combination Twisting of Thin-Walled Box Girders with Periodic Supports by the U-Transformation

Chen Senyan Cai Chengwu

Abstract The combination twisting of thin-walled box girder with periodic supports has been analyzed by the U-transform method. The uncoupled governing equations with boundary conditions for single substructure can be derived using the U-transformation. Some specific loading conditions are considered. The angular displacements and bimoments have been derived.

Keywords U-transformation, combination twisting, bimoment

* Department of Applied Mechanics and Engineering.