

一类孤子族的 Lax 表示^{*}

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摘 要 对一类特征值问题定义映射 e 给出一个 Lax 对 U, V_m , 其相应的 Lenard 序列 $K_{j-1}^{a_j} = J_j^a$ 不含逆微分算子 ∂^{-1} , 可显式求出线性表示的通解 $a_m = E_{G_s} g_{m-s}$, 从而得到了一类显式表示的孤子族 $T_m = X_m$.

关键词 孤子方程, Lax 表示, 符号计算

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众所周知, 利用 Lax 对可将特征值问题和孤子方程联系起来. 通过 Lenard 递推序列更可得一组孤子方程族. 利用这方法已有一系列文章得到了丰富的结果^[1-3]. 可惜的是解 Lenard 方程时往往含有逆微分算子 ∂^{-1} , 不易确定是否可得显式解, 是否有显式表示的孤子方程族.

本文讨论一类特征值问题^[4]

$$H_k = UH, \quad U = \lambda \begin{pmatrix} u & v + \lambda \\ v - \lambda & -u \end{pmatrix} \quad (1)$$

通过定义映射 e 给出一个 Lax 对 U, V_m . 其对应的 Lenard 递推序列方程不含逆微分算子 ∂^{-1} , 可具体显式求出其通解. 同时证明了其通解可通过某特解线性递推表示, 从而得到了显式表示的一类孤子方程族. 文中应用吴文俊数学机械化理论中的消元方法, 并应用了 MathematicaTM 数学软件编制的符号计算程序自动递推孤子方程族.

考虑特征方程 (1), 令 $U = \lambda e(T)$, 其中

$$e(T) = \begin{pmatrix} T^1 & T^2 - T^3 \\ T_+^2 & T^3 - T^1 \end{pmatrix}, \quad T = (T^1, T^2, T^3)^T$$

则对 (1) 式有 $U = \lambda e(T)$, $T = (u, v, -\lambda)^T$. 取 $V = \lambda e(U)$, $U = (U^1, U^2, U^3)^T$, 于是

$$[U, V] = \lambda^2 [e(T), e(U)] = \lambda^2 e(2T \otimes U) = \lambda^2 e(AU) \quad (2)$$

其中, $T = \text{diag}(1, 1, -1)$, $A = \begin{pmatrix} 0 & 2\lambda & 2v \\ -2\lambda & 0 & -2u \\ 2v & -2u & 0 \end{pmatrix}$

记 $U = SG$, $S = \text{diag}(1, 1, \lambda)$, $G = (G^1, G^2, G^3)^T$, $\partial_x = \frac{\partial}{\partial x}$, 则

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$$\text{这里 } K = \begin{pmatrix} \partial & 0 & 0 \\ 0 & \partial & 0 \\ -2\nu & 2u & \partial \end{pmatrix}, \quad J = \begin{pmatrix} 0 & 2 & 2\nu \\ -2 & 0 & -2u \\ 0 & 0 & 0 \end{pmatrix} \quad (3)$$

定义 Lenard 序列 $\{a_j\}$:

$$Ja_0 = 0, \quad Ka_{j-1} = Ja_j \quad (j = 1, 2, \dots) \quad (4)$$

定理 1 方程 (4) 有通解: $a_0 = e^0(u, v, -1)^T$

$$\begin{cases} a_1 = \left(\frac{1}{2}e^0\nu x + \frac{1}{2}e^0u(u^2 + v^2) + e^1u, \frac{1}{2}e^0v(u^2 + v^2) + e^1v, -\frac{1}{2}e^0(u^2 + v^2) - e^1 \right)^T \\ a_{m+1}^1 = -\frac{1}{2}\partial a_m^2 - u a_{m+1}^3 \\ a_{m+1}^2 = \frac{1}{2}\partial a_m^1 - v a_{m+1}^3 \\ a_{m+1}^3 = -\frac{1}{2}u a_m^1 - \frac{1}{2}v a_m^2 - \frac{1}{2}\sum_{j=1}^m \bar{e}^j(a_j^1 a_{m-j}^1 + a_j^2 a_{m-j}^2 - a_j^3 a_{m+1-j}^3) - e_{m+1} \end{cases} \quad (m = 1, 2, \dots) \quad (5)$$

其中, $e^0, e^1, \dots, e_{m+1}, \dots$ 为任意常数, $e^0 \neq 0, \bar{e} = e^0^{-1}$.

证明 a_0 可直接验证. 将 (4) 改写为

$$\begin{cases} a_{m+1}^1 = -\frac{1}{2}\partial a_m^2 - u a_{m+1}^3 \\ a_{m+1}^2 = \frac{1}{2}\partial a_m^1 - v a_{m+1}^3 \\ \partial a_m^3 = 2\nu a_m^1 - 2u a_m^2 \end{cases} \quad (6)$$

(5) 式的前两分式与 (6) 式相同. 现证 a_1 和 (5) 的第三分式成立.

$$\text{记 } f_m = (a_m^1, a_m^2)^T, \quad J = \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}, \quad E = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad a^* b = a^1 b^1 + a^2 b^2.$$

于是, $f_0 = e^0(u, v)^T, a^* b = b^* a, J a^* b = -a^* J b, J a^* a = 0, J a^* J b = a^* b, J J = E$.

(6) 式可化为

$$\begin{cases} f_{m+1} = \frac{1}{2}J f_m - \bar{e}^{a_3} f_0 \\ \partial f_m = -2J f_{m+1} - 2\bar{e}^{a_3} J f_0 \\ \partial a_m^3 = -2\bar{e} J f_0^* f_m = 2\bar{e} f_0^* J f_m \end{cases} \quad (7)$$

反复应用上述关系式, 得

$$\begin{aligned} J f_j^* f_{m+1-j} + \bar{e}^{a_3} J f_0^* f_{m+1-j} &= J f_j^* \left(\frac{1}{2}J f_{m-j} - \bar{e}^{a_3} f_0 \right) - \frac{1}{2} \bar{e}^3 \partial a_{m+1-j}^3 = \\ \frac{1}{2} f_j^* \partial f_{m-j} - a_{m+1-j}^3 J f_j^* f_0 - \frac{1}{2} \bar{e}^3 \partial a_{m+1-j}^3 &= \\ \frac{1}{2} f_j^* \partial f_{m-j} - \frac{1}{2} \partial a_j^3 a_{m-j}^3 - \frac{1}{2} \bar{e}^3 \partial a_{m+1-j}^3 &= \\ \frac{1}{2} \partial (f_j^* f_{m-j} - a_j^3 a_{m-j}^3) - \frac{1}{2} \partial f_j^* f_{m-j} &= \\ \frac{1}{2} \partial (f_j^* f_{m-j} - a_j^3 a_{m-j}^3) + J f_{j+1}^* f_{m-j} + \bar{e}^{a_3} J f_0^* f_{m-j} \end{aligned}$$

于是

$$Jf_0^* f_{m+1} + e^{\mathfrak{A}_0^3} Jf_0^* f_{m+1} = - \sum_{j=0}^m \partial(f_j^* f_{m-j} - \mathfrak{A}_j^3 \mathfrak{A}_{m+1-j}^3) + Jf_{m+1}^* f_0 + e^{\mathfrak{A}_{m+1}^3} Jf_0^* f_0$$

利用 $\mathfrak{A}_0^3 = -e_0$, $Jf_0^* f_0 = 0$ 及 (7) 式, 有 $\partial \mathfrak{A}_{m+1}^3 = - \sum_{j=0}^m \partial(f_j^* f_{m-j} - \mathfrak{A}_j^3 \mathfrak{A}_{m+1-j}^3)$,

即得通解

$$\mathfrak{A}_{m+1}^3 = - \sum_{j=0}^m \partial(f_j^* f_{m-j} - \mathfrak{A}_j^3 \mathfrak{A}_{m+1-j}^3) - 2e_{m+1} \quad (8)$$

其中, e_{m+1} 为任意常数. 整理之, 有

$$\begin{aligned} \mathfrak{A}_1^3 &= -\frac{1}{2} \partial f_0^* f_0 - e_1 = -\frac{1}{2} e_0 (u^2 + v^2) - e_1 \\ \mathfrak{A}_{m+1}^3 &= -\frac{1}{2} \partial f_0^* f_m - \sum_{j=1}^m \partial(f_j^* f_{m-j} - \mathfrak{A}_j^3 \mathfrak{A}_{m+1-j}^3) - e_{m+1} \\ &= -\frac{1}{2} u \mathfrak{A}_m^1 - \frac{1}{2} v \mathfrak{A}_m^2 - \sum_{j=1}^m \partial(\mathfrak{A}_j^1 \mathfrak{A}_{m-j}^1 + \mathfrak{A}_j^2 \mathfrak{A}_{m-j}^2 - \mathfrak{A}_j^3 \mathfrak{A}_{m+1-j}^3) - e_{m+1} \end{aligned}$$

证得 $\mathfrak{A}_j^3$ 及 (5) 式的第三分式成立. 定理证毕.

方程 (4) 的通解 (5) 中取 $e_0 = \bar{e} = 1$, $e_j = 0 (j > 0)$, 则得

推论 方程 (4) 有特解 $g_0 = (u, v, -1)^T$

$$\begin{cases} g^1 = (-\frac{1}{2} u + \frac{1}{2} u(u^2 + v^2), \frac{1}{2} u + \frac{1}{2} v(u^2 + v^2), -\frac{1}{2} (u^2 + v^2))^T \\ g_{m+1}^1 = -\frac{1}{2} \partial g_m^2 - u g_{m+1}^3 \\ g_{m+1}^2 = -\frac{1}{2} \partial g_m^1 - v g_{m+1}^3 \quad (m = 1, 2, \dots) \\ g_{m+1}^3 = \frac{1}{2} u g_m^1 - \frac{1}{2} v g_m^2 - \sum_{j=1}^m (g_j^1 g_{m-j}^1 + g_j^2 g_{m-j}^2 - g_j^3 g_{m+1-j}^3) \end{cases} \quad (9)$$

定理 2 方程 (4) 的通解 (5) 可由特解 (9) 表示为

$$\mathfrak{h}_m = c_0 g_{m+1} + c_1 g_{m+1} + \dots + c_m g_0 \quad (m = 0, 1, \dots) \quad (10)$$

其中, $c_0, c_1, \dots, c_m, \dots$ 为任意 (积分) 常数, $c_0 \neq 0$. c_i 与 e_j 有关系式

$$c_0 = e_0, c_1 = e_1, c_m = e_m - \frac{1}{2} c_0 \sum_{s=1}^{m-1} \mathfrak{A}_s c_{m-s} \quad (m = 2, 3, \dots) \quad (11)$$

证明 记 $\bar{g}_m = (g_m^1, g_m^2)^T$, 其中 g_m 为特解 (9). 应用定理 1 中证明的记号, 式 (8) 变为

$$\mathfrak{g}_{m+1}^3 = - \sum_{j=0}^m (\bar{g}_j^* \bar{g}_{m-j} - g_j^3 g_{m+1-j}^3) \quad (m = 0, 1, \dots) \quad (12)$$

显然, $m = 0, 1$ 时 (10) 式成立, $c_0 = e_0, c_1 = e_1$. 假设 (10), (11) 式当 $m = 0, 1, \dots, n$ 时成立. 则对任意常数 c_{n+1} . 定义

$$\mathfrak{h}_{n+1} = c_0 g_{n+1} + c_1 g_{n+1} + \dots + c_{n+1} g_0 \quad (13)$$

利用 $Jg_0 = 0$ 及 g_i 满足的关系式 (4) 有

$$K \mathfrak{h} = c_0 K g_{n+1} + c_1 K g_{n+1} + \dots + c_n K g_0 = c_0 J g_{n+1} + c_1 J g_{n+1} + \dots + c_n J g_1 + c_{n+1} J g_0 = J \mathfrak{h}_{n+1}$$

即 $\mathfrak{h}_{n+1}$ 满足 Lenard 方程 (4), 应用定理 1 的通解式 (8), 将 $m = 0, 1, \dots, n$ 时的 (10) 式代入, 重新整理, 同时利用关系式 (12), 可得

$$\mathfrak{h}_{n+1}^3 = -\frac{1}{2} \partial f_0^* f_n - \frac{1}{2} \sum_{j=1}^n (f_j^* f_{n-j} - \mathfrak{A}_j^3 \mathfrak{h}_{n+1-j}^3) - e_{n+1}$$

$$\begin{aligned}
& -\frac{1}{2}\bar{g}_0^* \sum_{s=0}^n c_s \bar{g}_{n-s} - \frac{1}{2} \sum_{j=1}^n \left(\sum_{e=0}^j c_s \bar{g}_{j-s} \right)^* \sum_{e=0}^{n-j} c_e \bar{g}_{n-j-e} - \sum_{s=0}^i c_s g_{j-s}^3 \\
& \left(\sum_{e=0}^{n-1-j} c_e g_{n-1-j-e}^3 \right) - \theta_{n-1} = \\
& -\frac{1}{2} \sum_{s=0}^n c_s \bar{g}_0^* \bar{g}_{n-s} - \frac{1}{2} \sum_{j=1}^n \sum_{s=0}^j \sum_{e=0}^{n-j} c_s c_e (\bar{g}_{j-s}^* \bar{g}_{n-j-e} - g_{j-s}^3 g_{n-1-j-e}^3) + \\
& \frac{1}{2} \sum_{j=1}^n \sum_{e=0}^i c_s c_{n-1-j} g_{j-s}^3 g_{0-s}^3 - \theta_{n-1} = \\
& -\sum_{s=0}^n \frac{1}{2} c_s \bar{g}_0^* \bar{g}_{n-s} - \frac{1}{2} \sum_{e=0}^{n-1} c_e \sum_{j=0}^{n-e} (\bar{g}_j^* \bar{g}_{n-e-j} - g_j^3 g_{n-1-e-j}^3) - \\
& \frac{1}{2} \sum_{s=1}^n \sum_{e=0}^{n-s} c_s c_{n-s} (\bar{g}_j^* \bar{g}_{n-e-j} - g_j^3 g_{n-1-s-e-j}^3) + \frac{1}{2} \sum_{s=1}^n \sum_{e=0}^{n-1-s} c_s c_e g_0^3 g_{n-1-s-e}^3 - \theta_{n-1} = \\
& \sum_{e=0}^{n-1} c_e \left(-\frac{1}{2} \bar{g}_0^* \bar{g}_{n-e} - \frac{1}{2} \sum_{j=0}^{n-e} (\bar{g}_j^* \bar{g}_{n-s-e-j} - g_j^3 g_{n-1-e-j}^3) - \frac{1}{2} c_0 \bar{g}_0^* \bar{g}_0 + \right. \\
& \left. \frac{1}{2} \sum_{s=1}^n \sum_{e=0}^{n-s} c_s c_{n-1-s} g_{n-1-s-e}^3 - \frac{1}{2} \sum_{s=1}^n \sum_{e=0}^{n-1-s} c_s c_e g_{n-1-s-e}^3 - \theta_{n-1} \right) = \\
& \sum_{e=0}^{n-1} c_e g_{n-1-e}^3 - c_n g_1^3 - \frac{1}{2} \sum_{s=1}^n c_s \theta_{n-1-s} g_0^3 - \theta_{n-1} = \sum_{e=0}^n c_e g_{n-1-e}^3 - \left(-\frac{1}{2} \sum_{s=1}^n c_s \theta_{n-1-s} + \theta_{n-1} \right) g_0^3
\end{aligned}$$

上式可写为

$$g_{n+1}^3 = c_0 g_n^3 + c_1 g_{n+1}^3 + \cdots + c_n g_1^3 + \theta_{n+1} g_0^3 \quad (14)$$

其中, θ_{n+1} 满足关系式 (11) $_{m=n+1}$. 因 c_j 与 e_j 是一一对应的, 故 (13) 式所定义的解 a_{n+1} 是方程 (4) 的通解. 事实上, 利用 (7) 和 (14) 式以及 (9) 式有

$$\begin{aligned}
f_{n+1} &= \frac{1}{2} J \partial f_n - e_{n+1}^3 f_0 = \frac{1}{2} J \sum_{s=0}^n c_s \bar{g}_{n-s} - \sum_{s=0}^{n+1} c_s g_{n+1-s}^3 \bar{g}_0 = \\
& \sum_{s=0}^n c_s \left(\frac{1}{2} J \partial \bar{g}_{n-s} - g_0^3 g_{n-1-s}^3 \right) - \theta_{n+1} g_0^3 = \sum_{s=0}^n c_s \bar{g}_{n-1-s} + \theta_{n+1} g_0^3
\end{aligned}$$

上式和 (14) 式证明了 (10) 当 $m=n+1$ 时成立. 即 (10)、(11) 式对任意 m 成立. 定理证毕.

现假设

$$G_m = G_m(\lambda, a) = \sum_{j=0}^{m-1} a_j \lambda^{2(m-1-j)} \quad (15)$$

易证得 $(K - \lambda^2 J) G_m = K a_{m-1} = J a_m$

记 $V_m = \lambda^e(S G_m)$. 定义孤子方程向量场为 $X_m = J g_m$. 则由 (15) 式 (3) 式和定理 2 有

$(K - \lambda^2 J) G_m = c_0 X_{m+1} + c_1 X_{m+1} + \cdots + c_m X_0 = X_m$, $\partial V_m - [U, V_m] = \lambda^e(S X_m)$. 零曲率方程

$$U_m - V_{m,x} + [U, V_m] = \lambda^e(T_m - S X_m) = 0 \quad (16)$$

等价于

$$T_m = S X_m = S J a_m = J a_m \quad (17)$$

当 a_m 取特解 g_m , 即 $c_0 = 1, c_1 = \cdots = c_m = 0$ 时上式变为 $T_m = S X_m = J g_m$, 即

$$\frac{\partial}{\partial t_m} \begin{pmatrix} u \\ v \\ -\lambda \end{pmatrix} = J g_m = \begin{pmatrix} 2g_m^2 + 2vg_m^3 \\ -2g_m^1 - 2ug_m^3 \\ 0 \end{pmatrix} = \begin{pmatrix} \partial_{g_m^1}^1 \\ \partial_{g_m^1}^2 \\ 0 \end{pmatrix} \quad (18)$$

它满足等谱条件 $\lambda_{l_m} = 0$.

由 V_m 的定义和零曲率方程 (16) 知, 如定义

$$H_m = V_m H = \sum_{j=0}^{m-1} e(S_j^a) \lambda^{2(m-j)-1} H \quad (19)$$

则方程 (1) 和 (19) 的解满足相容性条件. U 和 V_m 是孤子方程族 (17) 的一个 Lax 对.

由式 (9) 和 (18) 可递推计算 g_m 和 X_m . 求得显式孤子方程族. 下面是应用 MathematicaTM 数学软件计算出的部分结果, 其中 u' 表示 u_x , u'' 表示 u_{xx} , $u^{(n)}$ 表示 $\frac{\partial^n u}{\partial x^n}$, 等等.

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t_0} = u' \\ \frac{\partial v}{\partial t_0} = v' \end{array} \right\}, \left\{ \begin{array}{l} \frac{\partial u}{\partial t_1} = \frac{3}{2} u^2 u' + \frac{1}{2} v^2 u' + uv v' - \frac{1}{2} v'' \\ \frac{\partial v}{\partial t_1} = uv u' + \frac{1}{2} u^2 v' + \frac{3}{2} v^2 v' + \frac{1}{2} u'' \end{array} \right\}$$

$$\left\{ \begin{array}{l} \frac{\partial u}{\partial t_2} = \frac{25}{8} u^4 u' + \frac{15}{4} u^2 v^2 u' + \frac{5}{8} v^4 u' + \frac{1}{4} v u'^2 + \frac{5}{2} u^3 v v' + \frac{5}{2} u v^3 v' - \\ \quad \frac{7}{4} u u' v' - \frac{3}{2} v v'^2 + \frac{1}{4} u v u'' - u^2 v'' - \frac{3}{4} v^2 v'' - \frac{1}{4} u^{(3)} \\ \frac{\partial v}{\partial t_2} = \frac{5}{2} u^3 v u' + \frac{5}{2} u v^3 u' + \frac{3}{2} u u'^2 + \frac{5}{8} u^4 v' + \frac{15}{4} u^2 v^2 v' + \frac{25}{8} v^4 v' + \\ \quad \frac{7}{4} v u' v' - \frac{1}{4} u v'^2 + \frac{3}{4} u^2 u'' - \frac{1}{4} u v v'' + v^2 u'' - \frac{1}{4} v^{(3)} \end{array} \right.$$

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The Lax Representation of a Hierarchy of Soliton Equations

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Abstract For some eigenvalue problem, a map is defined to give the Lax pairs for a hierarchy of soliton equations. The inverse differential operator ∂^{-1} is not contained in the corresponding Lenard's equations $K^{q-1} = J^q$. The explicit general solutions of the Lenard's equations are linearly represented, by which the hierarchy of soliton equations is derived in explicit form.

Keywords soliton equation, Lax representation, symbolic operation

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